# Optimal Approximation and Characterization of the Error and Stability Functions in Banach Spaces* 

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Communicated by John R. Rice
Received April 24, 1969

## Introduction

In several problems of approximation theory we have to use the error function and the stability function of a space $P$ of approximants. (See, e.g. Refs. [2] and [7]). Namely, suppose $U$ and $V$ are Banach spaces such that

$$
\begin{equation*}
U \subset V \text { and the injection is compact and dense. } \tag{1}
\end{equation*}
$$

Let $P$ be a closed subspace of $V$. We define the error function by

$$
\begin{equation*}
e_{V}^{V}(P)=\sup _{u \in U} \inf _{v \in P} \frac{\|u-v\|_{V}}{\|u\|_{U}} . \tag{2}
\end{equation*}
$$

If $P$ is finite-dimensional, we define the stability function by

$$
\begin{equation*}
s_{U}^{v}(P)=\sup _{u \in P} \frac{\|u\|_{U}}{\|u\|_{V}} . \tag{3}
\end{equation*}
$$

( $S_{U}{ }^{r}(P)$ is finite, since all norms on a finite-dimensional space are equivalent). The motiviation for the present paper was the study of these functions.

First of all, they are related by the following duality relation:

$$
\begin{equation*}
e_{U}^{V}(P)=s_{U^{\prime}}^{V^{\prime}}\left(P^{\perp}\right) ; \quad s_{U}^{V}(P)=e_{U^{\prime}}^{V^{\prime}}\left(P^{\perp}\right), \tag{4}
\end{equation*}
$$

where $U^{\prime}, V^{\prime}$ are the duals of $U$ and $V$, respectively, and $P^{\perp}$ is the annihilator of $P$. On the other hand, they are eigenvalues of certain nonlinear operators (which are linear in case $U$ and $V$ are Hilbert spaces). For the sake of simpli-

[^0]city, we shall restrict our study to the case where $U$ and $V$ are smooth, uniformly convex, reflexive Banach spaces. In this case, there exists a unique duality mapping $J$ from $V$ onto $V^{\prime}$ (resp., $K$ from $U$ onto $U^{\prime}$ ) which is the one-to-one nonlinear mapping $J$ defined by
\[

$$
\begin{equation*}
(J u, u)=\|u\|_{V}^{2} ; \quad\|J u\|_{V^{\prime}}=\|u\|_{V} . \tag{5}
\end{equation*}
$$

\]

Then if $t$ is the (nonlinear) best approximation projector from $V$ onto $P$, defined by

$$
\begin{equation*}
\|u-t u\|_{\nu}=\inf _{v \in P}\|u-v\|_{\nu}, \tag{6}
\end{equation*}
$$

the error function is the square root of the largest eigenvalue of the operator $(1-t) K^{-1} J(1-t)$.

In order to characterize the stability function, we have to introduce another nonlinear projector $s$ from $V$ onto $P$ (the stabilization projector). If we define the cosine of the angle between two elements, $u$ and $v$, of $V$ by

$$
\begin{equation*}
\cos (u, v)=\frac{(J u, v)}{\|u\|\|v\|} \tag{7}
\end{equation*}
$$

then the projector $s$ is defined by

$$
\begin{equation*}
\cos (u, s u)=\sup _{v \in P} \cos (u, v) ; \quad\|s u\|=\cos (u, s u)\|u\| . \tag{8}
\end{equation*}
$$

These projectors $s$ and $t$ are linked by the following duality relation:

$$
\begin{equation*}
s=J^{-1}\left(1-t^{\perp}\right) J, \tag{9}
\end{equation*}
$$

where $t^{\perp}$ is the best approximation projector from $V^{\prime}$ onto $P^{\perp}$.
When $V$ is a Hilbert space, formula (9) shows that $s$ is the (Hilbertian) adjoint of $t ; s$ coincides with $t$, since the orthogonal projectors are the ones which are self-adjoint.

We shall prove, in general, that if $P$ is a finite-dimensional subspace of $U$, the stability function is the square root of the largest eigenvalue of the operator $s J^{-1} \mathrm{Ks}$. Incidentally, we shall prove the following two formulas. If $P=\operatorname{ker} r$ is the kernel of a continuous linear operator from $V$ onto a Banach space $E$, then

$$
t=1-p r, \quad \text { where } \quad p=J^{-1} r^{\prime}\left(r J^{-1} r^{\prime}\right)^{-1}
$$

and if $P=p E$ is the closed range of a linear isomorphism from a Banach space $E$ into $E$, then

$$
s=p r, \quad \text { where } \quad r=\left(p^{\prime} J p\right)^{-1} p^{\prime} J
$$

## 1. Duality Mapping and Cosines

### 1.1. Duality mapping

Let us recall the definition of the duality mapping from a Banach space $V$ into its dual $V^{\prime}$ (see Refs. [3, 4]).

By the Hahn-Banach theorem, we can associate with any $u$ of the unit sphere of $V$ a continuous linear form $J u$ of the unit sphere of its dual $V^{\prime}$ such that

$$
\begin{equation*}
(J u, u)=1 ; \quad\|J u\|_{*}=1 \tag{1.1}
\end{equation*}
$$

and we shall choose $J u$ so that

$$
\begin{equation*}
J(-u)=-J(u) \tag{1.2}
\end{equation*}
$$

Here $(f, v)$ denotes the duality pairing on $V^{\prime} \times V,\| \|$ is the norm of $V$, and $\left\|\|_{*}\right.$ is its dual norm.

We shall extend this mapping $J$, defined on the unit sphere, to all of $V$. Let $\alpha>1$. We set

$$
\begin{equation*}
J u=J_{V}^{\alpha} u=\|u\|^{\alpha-1} J\left(\frac{u}{\|u\|}\right) ; \quad J(0)=0 \tag{1.3}
\end{equation*}
$$

Such an operator is called an $(\alpha-)$ duality mapping from $V$ into $V^{\prime}$ and satisfies

$$
\begin{equation*}
\|J u\|_{*}=\|u\|^{\alpha-1} \tag{i}
\end{equation*}
$$

$$
\begin{equation*}
(J u, u)=\|u\|^{\alpha} \tag{ii}
\end{equation*}
$$

(iii) $\quad(J u-J v, u-v) \geqslant(\|u\|-\|v\|)\left(\|u\|^{\alpha-1}-\|v\|^{\alpha-1}\right) \geqslant 0$;

$$
\begin{equation*}
J(\lambda u)=|\lambda|^{\alpha-2} \lambda J u \tag{iv}
\end{equation*}
$$

We are mainly interested in the case where there exists a unique bijective duality mapping from $V$ onto $V^{\prime}$. This is the case when $V$ is a smooth, strictly convex, reflexive Banach space (briefly, an R.S. space), where
(i) A space $V$ is smooth iff each point of its unit sphere possesses a unique supporting hyperplane (equivalently: iff the norm $\|u\|$ is Gâteauxdifferentiable at each point of the unit sphere);
(ii) A space $V$ is strictly convex (or rotund) iff its unit sphere does not contain any line segment.

Let us recall (see Ref. [5]) that a reflexive Banach space is smooth iff its dual is strictly convex. Therefore, we have

Lemma 1.1. Let $V$ be an R.S. space. Then there exists a unique $\alpha$-duality
mapping $J=J_{V}{ }^{\alpha}$ which is one-to-one from $V$ onto $V^{\prime}$, and which is equal to the Gâteaux derivative of the functional $1 / \alpha\|v\|^{\alpha}$. Moreover,

$$
\begin{equation*}
\left(J_{V}^{\alpha}\right)^{-1}=J_{V^{\prime}}^{\alpha^{\prime}}, \quad \text { where } \quad \frac{1}{\alpha}+\frac{1}{\alpha^{\prime}}=1 \tag{1.5}
\end{equation*}
$$

The Lebesgue spaces $L^{\alpha}$ and the Sobolev spaces $W^{m, \alpha}$ are R.S. spaces for $1<\alpha<+\infty$. The $\alpha$-duality mapping of $L^{\alpha}$ is the map $J u=|u|^{\alpha-2} u$. A closed subspace and a factor space of an R. S. space are also R.S. spaces. The following lemma provides a tool for constructing duality mappings.

Lemma 1.2. Let $\varphi_{k}$ be a continuous linear operator from a space $V$ into an R.S. space $E_{k i}(k=0, \ldots, m)$ and let $V$ be a Banach space for the norm

$$
\begin{equation*}
\|v\|=\left(\sum_{k=0}^{m}\left\|\varphi_{k} v\right\|_{E_{k_{k}}}^{\alpha}\right)^{1 / \alpha}, \quad \alpha>1 \tag{1.6}
\end{equation*}
$$

Then $V$ is also an R.S. space. If $J_{k}$ is the $\alpha$-duality mapping from $E_{k}$ onto $E_{k}{ }^{\prime}$, the $\alpha$-duality mapping of $V$ is

$$
\begin{equation*}
J_{V}{ }^{\alpha}=\sum_{k=0}^{m} \varphi_{k}^{\prime} J_{E_{k}}^{\alpha} \varphi_{k} \tag{1.7}
\end{equation*}
$$

where $\varphi_{k}{ }^{\prime}$ denotes the transpose of $\varphi_{k}$.
If $V$ is a Hilbert space with the inner product $((u, v))$, the 2-duality mapping from $V$ onto $V^{\prime}$ is nothing else than the canonical isomorphism of the Riesz-Fischer theorem defined by

$$
\begin{equation*}
(J u, v)=((u, v)) ; \quad J \in \mathscr{L}\left(V, V^{\prime}\right) \tag{1.8}
\end{equation*}
$$

### 1.2. Cosine of two vectors of an R.S. space

We extend the usual definition of the cosine of the angle between two vectors of a Hilbert space in the following way: If $V$ is an R.S. space we define

$$
\begin{equation*}
\cos (u, v)=\cos _{V}(u, v)=\frac{\left(J_{V^{\alpha}} u, v\right)}{\|u\|^{\alpha-1}\|v\|}=\frac{\left(J_{V}^{\beta} u, v\right)}{\|u\|^{\beta-1}\|v\|} ; \quad \alpha>1 ; \quad \beta>1 \tag{1.9}
\end{equation*}
$$

It is a non-symmetric functional on $V \times V$ satisfying

$$
\begin{equation*}
|\cos (u, v)| \leqslant 1 ; \quad \cos (\lambda u, \mu v)=\cos (u, v) \quad \text { for } \quad \lambda, \mu \geqslant 0 \tag{1.10}
\end{equation*}
$$

and

$$
\begin{equation*}
\cos _{V}(u, v)=\cos _{V^{\prime}}(J v, J u) \tag{1.11}
\end{equation*}
$$

Remark 1.1. If $V$ is a normed linear space, we can also define the cosine
of the angle between two vectors, $u$ and $v$, of the unit ball in the following way:

$$
\begin{equation*}
\cos _{v}(u, v)=\lim _{\substack{\theta \rightarrow 0 \\ \theta>0}} \frac{(\|u+\theta v\|-\|u\|)}{\theta} \tag{1.12}
\end{equation*}
$$

### 1.3. Bounded homogeneous operators

We shall deal not only with continuous linear operators, but, more generally, with bounded homogeneous operators (briefly, $H$ operators), i.e., operators $A$ satisfying
(i) $A(\lambda u)=\lambda A u ; \quad \lambda$ a scalar,
(ii) $A$ maps bounded sets onto bounded sets.

We can associate with such an operator its norm

$$
\begin{equation*}
\|A\|=\sup _{\|u\| \leqslant 1}\|A u\|=\sup _{u \neq 0} \frac{\|A u\|}{\|u\|} \tag{1.14}
\end{equation*}
$$

and its kernel

$$
\begin{equation*}
\text { ker } A=\{u \text { such that } A u=0\} \tag{1.15}
\end{equation*}
$$

which is a symmetric cone.
We say that an $H$ operator $A$ is a projector if $A^{2}=A$.

## 2. Best Approximation and Stabilization Projectors

### 2.1. Best approximation projectors

Let $P$ be a closed subspace of a Banach space $V$ and consider the number

$$
\begin{equation*}
\inf _{v \in P}\|u-v\| . \tag{2.1}
\end{equation*}
$$

If $P$ is a reflexive subspace of $V$, this inf is achieved on $P$ at least once, and there exists at most one point of $P$ achieving this minimum if $V$ is strictly convex (see Ref. [6]). Therefore, when $V$ is a strictly convex reflexive Banach space, there exists a unique point $t u=t_{P} u \in P$ achieving the minimum (2.1) and we call $t=t_{P}$ the best approximation projector onto $P$.

Let us recall the following
Lemma 2.1 The best approximation projector $t$ is an $H$ projector satisfying

$$
\begin{equation*}
\|1-t\|=1 \tag{2.2}
\end{equation*}
$$

We set

$$
\begin{equation*}
P^{\oplus}=\operatorname{ker} t=(1-t) V \tag{2.3}
\end{equation*}
$$

We also recall the following (see Ref. [8]):
Lemma 2.2. If $V$ is an R.S. space, the best approximant tu is characterized by

$$
\begin{equation*}
t u \in P \quad \text { and } \quad J(u-t u) \in P^{\perp} \tag{2.4}
\end{equation*}
$$

Therefore, $J$ maps $P^{\oplus}$ onto $P^{\perp}$ and $P$ onto $P^{\perp \oplus}$.

### 2.2. Stabilization projectors

Let us consider the number

$$
\begin{equation*}
\lambda=\sup _{v \in P} \cos (u, v)=\sup _{v \in P} \frac{(J u, v)}{\|u\|^{\alpha-1}\|v\|} \tag{2.5}
\end{equation*}
$$

we can restrict $v$ to belong to the unit sphere of $V$. Observe that $\cos (u, v)=0$ on $P$ iff $u$ belongs to $P \oplus$. Otherwise, the supremum is positive.

If $P$ is a reflexive subspace, this sup is achieved at least once on the unit sphere. On the other hand, the set of points of the unit sphere of $P$ achieving this sup is convex. Indeed, if $v_{0}$ and $v_{1}$ are such points, set

$$
v_{\alpha}=\frac{(1-\alpha) v_{0}+\alpha v_{1}}{\left\|(1-\alpha) v_{0}+\alpha v_{1}\right\|}, \quad 0 \leqslant \alpha \leqslant 1
$$

Then

$$
\begin{equation*}
\cos \left(u, v_{\alpha}\right)=\frac{\lambda}{\left\|(1-\alpha) v_{0}+\alpha v_{1}\right\|} \leqslant \lambda . \tag{2.6}
\end{equation*}
$$

This implies that $\left\|(1-\alpha) v_{0}+\alpha v_{1}\right\| \geqslant 1$ and that $v_{\alpha}$ also achieves the sup.
Therefore, as in the best approximation problem, there exists a unique point $s^{0}(u)=s_{P}^{0}(u)$ of the unit sphere of $P$ achieving the sup in (2.5), when $V$ is a strictly convex reflexive Banach space.

In this case, we set

$$
s u=s_{P}^{\alpha}(u)=\left\{\begin{array}{l}
0 \quad \text { iff } \quad u \in P^{\oplus},  \tag{2.7}\\
\|u\| \cos \left(u, s_{P}^{0}(u)\right)^{\alpha^{\prime}-1} s_{P}^{0}(u) \quad \text { otherwise },
\end{array}\right.
$$

and we call ${s_{P}}^{\alpha}$ the $\alpha$-stabilization projector onto $P$. Indeed, as one can check, we have

Lemma 2.3. The operator $s_{P}{ }^{\alpha}$, defined by (2.7), is an H projector of norm 1 , satisfying

$$
\begin{equation*}
\left\|s_{P}^{\alpha} u\right\|^{\alpha-1}=\cos \left(u, s_{P}^{\alpha} u\right)\|u\|^{\alpha-1} \leqslant\|u\|^{\alpha-1} \tag{2.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{ker} s_{P}^{\alpha}=\left(1-s_{P}^{\alpha}\right) V=P^{\oplus} . \tag{2.9}
\end{equation*}
$$

When $V$ is a Hilbert space (and $\alpha=2$ ) the best approximation operator and the stabilization projector coincide with the orthogonal projector onto $P$ (see the remark following Lemma 1.2). When $V$ is an R.S. space, then, as we shall see, in some sense $s_{P}{ }^{\alpha}$ is the "adjoint" of $t_{p}$.

Theorem 2.1. Let $V$ be an R.S. space, $P$ a closed subspace of $V$, and $P^{\perp}$ its annihilator. Let $J=J_{V}{ }^{\alpha}$ be the $\alpha$-duality mapping from $V$ onto $V^{\prime}$. Then the stabilization projector $s=s_{P}{ }^{\alpha}$ onto $P$ and the best approximation projector $t^{\perp}=t_{P^{\perp}}$ onto $P^{\perp}$, in $V^{\prime}$, are related by the formula

$$
\begin{equation*}
s=J^{-1}\left(1-t^{\perp}\right) J \tag{2.10}
\end{equation*}
$$

Indeed, to maximize $\cos (u, v)$ on $P$ amounts to maximizing, on $P$, the function

$$
\begin{equation*}
\rho(v)=\|u\|^{\alpha(\alpha-1)}|\cos (u, v)|^{\alpha-1} \cos (u, v)=\frac{|(J u, v)|^{\alpha-1}(J u, v)}{\|v\|^{\alpha}} \tag{2.11}
\end{equation*}
$$

where $u \notin P^{\oplus}$. Since $V$ is smooth, the functional $\rho(v)$ is Gâteaux-differentiable at every point $v \neq 0$ and its derivative at $v_{0}$ is

$$
\begin{equation*}
L v_{0}=\frac{\left\|v_{0}\right\|^{\alpha}\left|\left(J u, v_{0}\right)\right|^{\alpha-1} J u-\left|\left(J u, v_{0}\right)\right|^{\alpha-1}\left(J u, v_{0}\right) J v_{0}}{\left\|v_{0}\right\|^{2 \alpha}} \tag{2.12}
\end{equation*}
$$

Let $v_{0}=s_{p}{ }^{0}(u)$ be the point of the unit sphere of $P$ achieving the sup of $\rho(v)$ on $P$. Since $\rho(v) \leqslant \rho\left(v_{0}\right)$ for any $v$ in $P$, we deduce that $\left(L v_{0}, v\right)=0$ for any such $v$, and thus, that $L v_{0}$ belongs to $P^{\perp}$. In other words, there exists an $f$ belonging to $P^{\perp}$ such that

$$
\begin{equation*}
J u-\left(J u, v_{0}\right) J v_{0}=f \tag{2.13}
\end{equation*}
$$

But since $J u-f=\left(J u, v_{0}\right) J v_{0}$ belongs to $P^{\perp \oplus}$ (by the Lemma 2.2), we deduce that $f=t^{\perp} J u=t_{P \perp} J u$. Therefore, $\left(J u, v_{0}\right) J v_{0}=\left(1-t^{\perp}\right) J u$ and, since $v_{0}=s_{P}{ }^{0}(u)$,

$$
J^{-1}\left(1-t^{\perp}\right) J u=\left|\left(J u, v_{0}\right)\right|^{\alpha^{\prime}-2}\left(J u, v_{0}\right) v_{0}=s_{P}^{\alpha}(u)
$$

Conversely, let us assume that $s_{P}{ }^{\alpha}$ is defined by

$$
\begin{equation*}
J s_{P}{ }^{\alpha}(u)=\left(1-t^{\perp}\right) J u \tag{2.14}
\end{equation*}
$$

If $u$ belongs to $P^{\oplus}$, it follows that $s_{P}^{\alpha}(u)=0$. Otherwise,

$$
\left(J s_{P}^{\alpha}(u)-J u, v\right)=-\left(t^{\perp} J u, v\right)=0 \quad \text { for any } \quad v \text { in } P
$$

Taking $v=s_{P}{ }^{\alpha}(u)$, we get

$$
\cos \left(u, s_{P}^{\alpha}(u)\right)=\frac{\left(J u, s_{P}^{\alpha}(u)\right)}{\|u\|^{\alpha-1}\left\|s_{P}^{\alpha}(u)\right\|}=\frac{\left(J s_{P}^{\alpha}(u), s_{P}^{\alpha}(u)\right)}{\left\|s_{P}^{\alpha}(u)\right\|\|u\|^{\alpha-1}}=\frac{\left\|s_{P}^{\alpha}(u)\right\|^{\alpha-1}}{\|u\|^{\alpha-1}}
$$

and (2.8) is satisfied. On the other hand, $s_{P}{ }^{\alpha}(u)$ maximizes $\cos (u, v)$ on $P$, since

$$
|\cos (u, v)|=\frac{|(J u, v)|}{\|u\|^{\alpha-1}\|v\|}=\frac{\left|\left(J s_{P}^{\alpha}(u), v\right)\right|}{\|u\|^{\alpha-1}\|v\|} \leqslant \frac{\left\|s_{P}^{\alpha}(u)\right\|^{\alpha-1}}{\|u\|^{\alpha-1}}=\cos \left(u, s_{P}^{\alpha} u\right)
$$

Therefore, $s_{P}{ }^{\alpha}(u)$, defined by (2.14), satisfies (2.7).
Remark 2.1. If $V$ is a Hilbert space, $1-t^{\perp}$ is equal to the transpose $t^{\prime}$ of the orthogonal projector $t$ onto $P$, and $J^{-1} t^{\prime} J$ is the adjoint of the operator $t$. Since $t$ is self-adjoint, $s=t$.

### 2.3. Characterization of the best approximation projectors

Suppose a closed subspace $R$ is the kernel of a continuous linear operator $r$, mapping $V$ onto a Banach space $E$,

$$
\begin{equation*}
R=\operatorname{ker} r ; \quad r \in \mathscr{L}(V, E) ; \quad r(V)=E \tag{2.15}
\end{equation*}
$$

we shall prove a formula expressing the best approximation projector $t=t_{R}$ on $R$ in terms of $r$ and the duality mapping $J$ from $V$ onto $V^{\prime}$.

Theorem 2.2. Assume (2.15) and that $V$ is an R.S. space. Then the best approximation projector $t=t_{R}$ onto $R$ satisfies

$$
\begin{equation*}
t=(1-p r) \tag{2.16}
\end{equation*}
$$

where $p$ is the $H$ operator from $E$ onto $R^{\oplus}$, defined by

$$
\begin{equation*}
p=J^{-1} r^{\prime}\left(r J^{-1} r^{\prime}\right)^{-1} \tag{2.17}
\end{equation*}
$$

The proof is quite obvious. We have, first of all, to verify that $r J^{-1} r^{\prime}$ is invertible. But this is a consequence of Lemma 1.2, which implies that $r J^{-1} r^{\prime}$ is the duality mapping from $E^{\prime}$ onto $E$, when $E^{\prime}$ is equipped with the norm $\left\|e^{\prime}\right\|_{E^{\prime}}=\left\|r^{\prime} e^{\prime}\right\|_{V^{\prime}}$, and $E$, with its dual norm. By a theorem of Banach, $E$ is an R.S. space. Therefore, by Lemma 1.1, $r J^{-1} r^{\prime}$ is invertible, and the formula (2.17) is meaningful. Thus, $t u$ belongs to $R$ since

$$
r t u=r u-r p r u=0
$$

and $t u$ is the best approximant of $u$ since, by Lemma $2.2, J(u-t u)=$ $J(p r u)=r^{\prime}\left(r J^{-1} r^{\prime}\right)^{-1}$ belongs to $r^{\prime} E^{\prime}=R^{\perp}$.

Incidentally, we solve the problem of "optimal interpolation" in Banach spaces (see, e.g., Ref. [1]) which amounts to finding a right inverse of $r$ having "minimal norm."

For this purpose, let us associate with $r$ and the norm of $V$ the following norm on $E$ :

$$
\begin{equation*}
\|e\|_{E}=\sup _{e^{\prime} \in E^{\prime}} \frac{\left|\left(e^{\prime}, e\right)\right|}{\left\|r^{\prime} e^{\prime}\right\|_{V^{\prime}}} . \tag{2.18}
\end{equation*}
$$

For this norm, $r$ is an operator of norm 1. Therefore:
Corollary 2.1. Let $r$ be a given operator from an R.S. space $V$ onto a Banach space E, equipped with the norm (2.18). Then

$$
\begin{equation*}
p=J^{-1} r^{\prime}\left(r J^{-1} r^{\prime}\right)^{-1} \tag{2.19}
\end{equation*}
$$

is a right inverse of $r$,

$$
\begin{equation*}
r p e=e \quad \text { for any } \quad e \in E, \tag{2.20}
\end{equation*}
$$

p is an H-isometry,

$$
\begin{equation*}
\|p e\|_{V}=\|e\|_{E} \quad \text { for any } \quad e \in E \tag{2.21}
\end{equation*}
$$

and

$$
\begin{equation*}
\|p e\|_{V} \leqslant\|u\|_{V} \quad \text { for any } u \text { such that } r u=e \tag{2.22}
\end{equation*}
$$

Indeed, $\|e\|_{E}$, defined by (2.18), is nothing else than the dual norm of $\left\|e^{\prime}\right\|_{E}=\left\|r^{\prime} e^{\prime}\right\|_{V^{\prime}}$. Therefore, we can set

$$
J_{E}=J_{E}^{\alpha}=\left(J_{E}^{\alpha^{\prime}}\right)^{-1}=\left(r J^{-1} r^{\prime}\right)^{-1}
$$

Then (2.21) follows from

$$
\|p e\|^{\alpha}=(J p e, p e)=\left(r^{\prime} J_{E}^{\alpha} e, p e\right)=\left(J_{E}^{\alpha} e, e\right)=\|e\|_{E}^{\alpha},
$$

and (2.22) follows from

$$
\begin{aligned}
\|p e\|^{\alpha} & =\left(J_{E}^{\alpha} e, e\right)=\left(J_{E}^{\alpha} e, r u\right)=\left(r^{\prime} J_{E}^{\alpha} e, u\right) \\
& =(J p e, u) \leqslant\|p e\|^{\alpha-1}\|u\| .
\end{aligned}
$$

Let us extend this result to general normed linear spaces. Assume that
(i) $E$ is reflexive;
(ii) There exists a duality mapping $L=L^{\alpha}{ }_{v^{\prime}}$ from $V^{\prime}$ into $V^{\prime \prime}$ such that $L r^{\prime} E^{\prime} \subset V$.
By Lemma $1.2, L_{E}=r L r^{\prime}$ is a duality mapping from $E^{\prime}$ onto $E$ (by Ref. [4]). Among the duality mappings from $E$ onto $E^{\prime}$, let us denote by $J_{E}$ the one which satisfies

$$
\begin{equation*}
L_{E} J_{E} e=e \quad \text { for any } e \in E . \tag{2.24}
\end{equation*}
$$

Corollary 2.2. Let $R=\mathrm{ker} r$ be a closed subspace of a normed linear space $V$, where $r$ maps $V$ onto $E$. If we assume (2.23), the operator $p$, mapping $E$ into $V$, defined by

$$
\begin{equation*}
p=J^{-1} r^{\prime} J_{E}, \tag{2.25}
\end{equation*}
$$

satisfies the properties (2.20), (2.21), and (2.22) of Corollary 2.1.
Remark 2.2. In the same way as in Ref. [1], we can extend the last corollary to the case where $V$ is equipped with a seminorm $p(v)$, instead of a norm || $\mid$.

### 2.4. Characterization of the stabilization projector

Let us assume now that a closed subspace $P$ of $V$ is the range of an isomorphism $p$ from a Banach space $E$ into $V$.
We shall compute the stabilization projector $s=s_{P}{ }^{\alpha}$ in terms of $p$ and of the duality mapping $J=J_{V}{ }^{\alpha}$ from $V$ onto $V^{\prime}$.

Theorem 2.3. If $V$ is an R.S. space, the stabilization projector $s$ onto $P=p E$ is given by

$$
\begin{equation*}
s=p r \tag{2.26}
\end{equation*}
$$

where $r=r^{\alpha}$ is the $H$ operator from $V$ onto $E$ with ker $r=P^{\oplus}$, defined by

$$
\begin{equation*}
r=\left(p^{\prime} J p\right)^{-1} p^{\prime} J . \tag{2.27}
\end{equation*}
$$

First of all, $p^{\prime} J p$ is equal to the duality mapping $J_{E}=J_{E}{ }^{\alpha}$ of $E$ when it is supplied with the norm $\|e\|=\|p e\|\left(\text { Lemma 1.2). Therefore ( } p^{\prime} J p\right)_{E}^{-1}=J_{\alpha^{\prime}}^{E^{\prime}}$, and thus $r p=1$, and $s=p r$ is an $H$ projector onto $P$.
Since $P^{\perp}=\operatorname{ker} p^{\prime}$, we deduce from Theorem 2.2 that

$$
1-t^{\perp}=J p\left(p^{\prime} J p\right)^{-1} p^{\prime}
$$

and thus

$$
s=p r=J^{-1}\left(1-t^{\perp}\right) J .
$$

Theorem 2.1 implies that $s$ is the stabilization projector onto $P$.

Corollary 2.3. Among the left-inverse $H$ operators of $p$, the operator $r$, defined by (2.27), is the one which achieves the minimal norm (equal to one).

Indeed, $\|r u\|_{E}=\|p r u\|_{V}=\|s u\|_{V} \leqslant\|u\|$, by Lemma 2.3. Therefore, $\|r\|=1$, and any left inverse of $p$ has a norm greater than one. Let us notice the following formula.

Corollary 2.4. The operator $r$, defined by (2.27), is related to $p$ by

$$
\begin{equation*}
\cos _{v}(u, p e)=\frac{\|r u\|^{\alpha-1}}{\|u\|^{\alpha-1}} \cos (r u, e) ; \quad u \in V, \quad e \in E \tag{2.28}
\end{equation*}
$$

## 3. Characterization of the Error and Stability Functions

### 3.1. Stability functions and error functions of a subspace $P$

Let us consider two Banach spaces $U$ and $V$ such that

$$
\begin{equation*}
U \text { is contained in } V \text { with a stronger topology; } U \text { is dense in } V . \tag{3.1}
\end{equation*}
$$

Let $P$ be a closed subspace of $U$ and $V$. We associate with $P$ the following functionals:
(i) the error function

$$
\begin{equation*}
e_{U}^{V}(P)=\sup _{u \in U} \inf _{v \in P} \frac{\|u-v\|_{V}}{\|u\|_{U}} \tag{3.2}
\end{equation*}
$$

(ii) the stability function

$$
\begin{equation*}
s_{U}^{V}(P)=\sup _{v \in P} \frac{\|v\|_{U}}{\|v\|_{V}} \tag{3.3}
\end{equation*}
$$

There is a dual relation between these two functionals.
Theorem 3.1. Let us Assume (3.1) and let $P^{\perp}$ be the annihilator of $P$. Then
(i) $e_{U}{ }^{V}(P)=s_{U^{\prime}}^{V^{\prime}}\left(P^{\perp}\right) ;$
(ii) $s_{U}^{V}(P)=e_{U^{\prime}}^{V^{\prime}}\left(P^{\perp}\right)$.

Indeed, let
(i) $j$ be the canonical injection from $U$ into $V$;
(ii) $\varphi$ be the canonical surjection from $V$ onto $V / P$.

Then $e_{U}{ }^{V}(P)$ is the norm, in $\mathscr{L}(U, V / P)$, of the operator $\varphi \cdot j$. By transposition, $e_{U}{ }^{V}(P)$ is the norm of $j^{\prime} \varphi^{\prime}$ in $\left.\mathscr{L}(V / P)^{\prime}, U^{\prime}\right)$.

But $(V / P)^{\prime}$ is isometric to $P^{\perp}$, and so $\varphi^{\prime}$ can be identified with the canonical injection from $P^{\perp}$ into $V^{\prime}$. Since $U$ is dense in $V$, we can identify $V^{\prime}$ with a subspace of $U^{\prime}$, and $j^{\prime}$ becomes the canonical injection from $U^{\prime}$ into $V^{\prime}$. Therefore

$$
e_{U}{ }^{v}(P)=\left\|j^{\prime} \varphi^{\prime}\right\|_{\mathscr{L}\left(P \perp, U^{\prime}\right)}=\sup _{f \in P^{\perp}}\|f\|_{U^{\prime}}\|f\|_{V^{\prime}}=s_{U^{\prime}}^{V^{\prime}\left(P^{\perp}\right)}
$$

One can prove (3.4(ii)) in the same way.

### 3.2. Computation of the norm of an operator

Let $X$ and $Y$ be R.S. spaces, $Z$ a Banach space, and
(i) $A$ a linear operator from $Z$ into $X$;
(ii) $B$ an isomorphism from $Z$ into $Y$.

Let us set

$$
\begin{equation*}
d(A, B)=\sup _{u \in \mathcal{Z}} \frac{\|A u\|_{X}}{\|B u\|_{Y}} . \tag{3.7}
\end{equation*}
$$

By Lemma 1.2 , the operator $B^{\prime} J_{Y}{ }^{\alpha} B$, mapping $Z$ into $Z^{\prime}$, is invertible, since it is actually the duality mapping of $Z$, equipped with the norm $\|B u\|_{Y}$.

We shall need the following:
Theorem 3.2. Assume that the sup in (3.7) is achieved at a point $u_{0}$ satisfying $\left\|B u_{0}\right\|_{Y}=1$. Then $d(A, B)$ is the $\alpha^{\prime}$-th root of the largest eigenvalue of the operator $\left(B^{\prime} J_{Y}{ }^{\alpha} B\right)^{-1}\left(A^{\prime} J_{X}{ }^{\alpha} A\right)$,

$$
\begin{equation*}
\left(B^{\prime} J_{Y^{\alpha}}^{\alpha} B\right)^{-1}\left(A^{\prime} J_{X}^{\alpha} A\right) u_{0}=d(A, B)^{\alpha^{\prime}} u_{0} ; \quad\left\|B u_{0}\right\|_{Y}=1 \tag{3.8}
\end{equation*}
$$

Consider the functional

$$
\begin{equation*}
\rho(v)=\frac{\|A v\|_{X}^{\alpha}}{\|B v\|_{Y}^{\alpha}} . \tag{3.9}
\end{equation*}
$$

Since $X$ and $Y$ are smooth, this functional has a Gâteaux derivative $L u$ (for $u \neq 0$ ) satisfying

$$
L u=\frac{\|B u\|_{Y}^{\alpha} A^{\prime} J_{X}^{\alpha} A u-\|A u\|_{X}^{\alpha} B^{\prime} J_{Y}^{\alpha} B u}{\|B u\|_{Y}^{2 \alpha}} .
$$

By hypothesis, there exists $u_{0}$ such that

$$
\left\|B u_{0}\right\|_{Y}=1 ; \quad d(A, B)^{\alpha}=\rho\left(u_{0}\right) \geqslant \rho(v) \text { for any } \quad v \neq 0 .
$$

Therefore, for any $v \neq 0,\left(L u_{0}, v\right)=0$ and thus,

$$
L u_{0}=A^{\prime} J_{X}^{\alpha} A u_{0}-d(A, B)^{\alpha} B^{\prime} J_{Y}^{\alpha} B u_{0}=0
$$

Hence $d(A, B)^{\alpha^{\prime}}$ is an eigenvalue of the operator $\left(B^{\prime} J_{Y}{ }^{\alpha} B\right)^{-1} A^{\prime} J_{X}{ }^{\alpha} A$. It is the largest one, since if $d^{\alpha^{\prime}}$ is any positive eigenvalue, we deduce from

$$
A^{\prime} J_{X}^{\alpha} A u=d^{\alpha} B^{\prime} J_{Y}^{\alpha} B u
$$

the equality

$$
\|A u\|_{X}^{\alpha}=d^{\alpha}\|B u\|_{Y}^{\alpha}
$$

Remark 3.1. We shall apply, in a forthcoming paper, this kind of result to the problem of existence of eigenvalues of nonlinear operators.

### 3.3. Characterization of the stability and error functions

Let $U$ and $V$ be R.S. spaces such that

$$
\begin{equation*}
U \subset V, \text { he injection being compact and dense, } \tag{3.10}
\end{equation*}
$$

and let $K=K_{U}{ }^{\alpha}$ and $J=J_{V}{ }^{\alpha}$ be the duality mappings of $U$ and $V$, respectively.

Let $P$ be a closed subspace of $V$.
Let $t=t_{P}$ be the best-approximation projector onto $P($ in $V), P^{\oplus}=\operatorname{ker} t$, and $s=s_{P}{ }^{\alpha}$ the stabilization projector onto $P$ (in $V$ ).

Theorem 3.3. Let us assume (3.10). Then $e_{U}{ }^{V}(P)$ is the $\alpha^{\prime}$-th root of the largest eigenvalue of the operator $(1-t) K^{-1} J(1-t)$, mapping $P^{\oplus}$ into itself,

$$
\begin{equation*}
(1-t) K^{-1} J(1-t) u=e_{U}^{V}(P)^{\alpha^{\prime}} u ; \quad u \in P^{\oplus} \tag{3.11}
\end{equation*}
$$

Furthermore, if we assume

$$
\begin{equation*}
P \text { is a finite-dimensional subspace contained in } U \text { such that } K P \subset V^{\prime} \tag{3.12}
\end{equation*}
$$

then $s_{U}{ }^{\nu}(P)$ is the $\alpha^{\prime}$-th root of the largest eigenvalue of the operator $s J^{-1} K s$, mapping $P$ into itself,

$$
\begin{equation*}
s J^{-1} K s v=s_{U}^{v}(P)^{\alpha^{\prime}} v ; \quad v \in P \tag{3.13}
\end{equation*}
$$

Let us write $P=\operatorname{ker} r$, where $r$ is a continuous linear operator from $V$ onto a Banach space $E$ (for instance, we can take $E=V / P$ and $r$ the canonical surjection from $V$ onto $V / P$ ). Then $P^{\perp}=r^{\prime} E^{\prime}$ and, by Theorem 3.1,

$$
e_{U}^{V}(P)^{\alpha^{\prime}}=s_{U^{\prime}}^{V^{\prime}}(P)^{\alpha^{\prime}}=\sup _{e \in E^{\prime}} \frac{\left\|r^{\prime} e\right\|_{V^{\prime}}^{\alpha^{\prime}}}{\left\|r^{\prime} e\right\|_{V^{\prime}}^{\alpha^{\prime}}} ; \quad \frac{1}{\alpha}+\frac{1}{\alpha^{\prime}}=1 .
$$

By (3.10), the injection from $V^{\prime}$ into $U^{\prime}$ is compact and the sup is achieved at some point $e$. Therefore, by Theorem 3.2, $e_{U}^{V}(P)^{\alpha}$ is the largest eigenvalue of

$$
\left(r J^{-1} r^{\prime}\right)^{-1} r K^{-1} r^{\prime} e=e_{U}^{V}(P)^{\alpha} e,
$$

or, equivalently, of the operator

$$
\begin{equation*}
J^{-1} r^{\prime}\left(r J^{-1} r^{\prime}\right)^{-1} r K^{-1} J J^{-1} r^{\prime} e=e_{U}^{V}(P)^{\alpha^{\prime}} \cdot J^{-1} r^{\prime} e \tag{3.14}
\end{equation*}
$$

since $r^{\prime}$ is an isomorphism from $E^{\prime}$ onto $P^{\perp}$ and $J$ is a bijection from $V$ onto $V^{\prime}$.

Therefore, $u=J^{-1} r^{\prime} e$ belongs to $P^{\oplus}$ (by Lemma 2.2), and we can write (3.14) in the form

$$
(1-t) K^{-1} J(1-t) u=e_{U}^{v}(P)^{\alpha^{\prime}} u
$$

by Theorem 2.2.
Let us now assume (3.12) and write $P=p E$, where $p$ is an isomorphism from $E$ onto $P$ (we can choose, for instance, $E=P$, and $p$ the canonical injection).

Since the dimension of $P$ is finite, the supremum in

$$
\begin{equation*}
s_{U}^{V}(P)^{\alpha}=\sup _{e \in E} \frac{\|p e\|_{U}^{\alpha}}{\|p e\|_{V}^{\alpha}} \tag{3.15}
\end{equation*}
$$

is achieved at some point $e$. Therefore, by Theorem $3.2, s_{U}{ }^{V}(P)^{\alpha^{\prime}}$ is the largest eigenvalue of the operator

$$
\begin{equation*}
\left(p^{\prime} J p\right)^{-1} p^{\prime} K p e=s_{U}^{V}(P)^{\alpha^{\prime}} e \tag{3.16}
\end{equation*}
$$

or, equivalently, of the operator

$$
\begin{equation*}
p\left(p^{\prime} J p\right)^{-1} p^{\prime} J J^{-1} K p e=s_{U}^{V}(P)^{\alpha^{\prime}} p e \tag{3.17}
\end{equation*}
$$

since $p$ is an isomorphism from $E$ onto $P$ and since $J J^{-1}$ is the identity on $K P$, by (3.12). Therefore $u=p e$ belongs to $P, s u=u$, and, by Theorem 2.3, we can write (3.17) in the form

$$
s J^{-1} K s u=s_{U}^{V}(P)^{\alpha^{\prime}} u ; \quad u \in P
$$

Corollary 3.1. Let $u$ be an eigenvector of $(1-t) K^{-1} J(1-t)$, associated with $e_{U}^{V}(P)^{\alpha^{\prime}}$. Then $u$ belongs also to $P \oplus$.

Indeed, if $v$ belongs to $P$, we have

$$
\frac{\|u+v-t(u+v)\|_{V}^{\alpha}}{\|u+v\|_{U}^{\alpha}} \leqslant \frac{\|u\|_{V}^{\alpha}}{\|u\|_{U}^{\alpha}} \leqslant \frac{\|u+(v-t(u+v))\|_{V}^{\alpha}}{\|u\|_{U}^{\alpha}} .
$$

Therefore, $\|u\|_{\alpha}^{U} \leqslant\|u+v\|_{\alpha}^{U}$ for any $v$ in $U$.

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[^0]:    * Sponsored by the Mathematics Research Center, United States Army, Madison, Wisconsin, under Contract No. DA-31-124-ARO-D-462.
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